CALL FOR CONTRIBUTIONS



Jeju Korea

October 27-29th www.theiccais.org





Important Dates

2025

May 1st

- Workshop/Special session

June 30th August 15th

- Paper submission

September 1st September 8th

- Notification of acceptance

September 19th September 26th - Camera-ready submission

September 30th

- Early-bird registration

October 27-29th

- Event/Site registration

The 14th International Conference on Control. **Automation and Information Sciences**

The 14th International Conference on Control, Automation and Information Sciences (ICCAIS 2025) will be held from October 27 to 29, 2025 in Jeju, Korea's largest island with stunning landscapes and natural heritage. This conference aims to provide a forum for sharing the latest research achievements and future development directions in control, automation and information sciences. All authors are cordially invited to submit articles on research findings. scientific investigations and achievements. The conference proceedings will be submitted for Scopus Indexing and the Digital Library (all proceedings from previous conferences are Scopus indexed and available on **IEEE**Xplore). Selected be invited for submission to SCI-indexed Journals after extension.

Paper Submission

Prospective authors are invited to submit papers electronically via a peerreview system found at the conference website: www.theiccais.org, where the manuscript template and submission instructions are available.

Workshops, Special Sessions & Invited Talks/Tutorials

We invite proposals for feature Workshop, Special Session or Technical Tutorial on the latest research outcomes relevant to the conference theme. They are an important, highly popular, tradition of ICCAIS each year.

Topics include but are not limited to:

- **Intelligent Control**
- Information Fusion
- **Precision Guidance**
- **Machine Learning**
- Al Control Algorithms
- **Data Mining**

- Linear / Nonlinear Filtering
- Finite Set Statistics
- Target Tracking
- Signal Processing & Applications
- Sensors and Instrumentations
- **Real-time Communication**

- Mobile Robots
- Grasping and Manipulation
- Soft Robots; actuator, sensor & control
- Positioning
- SLAM
- Autonomous Mobility

- Power Electronics
- **Energy Conversion**
- Smart Home/Buildings/Cities
- Forecasting & Simulation
- Networked Systems
- **Electric Vehicle Integration**









